

# Methodology to Compare Time Stamping Accuracy

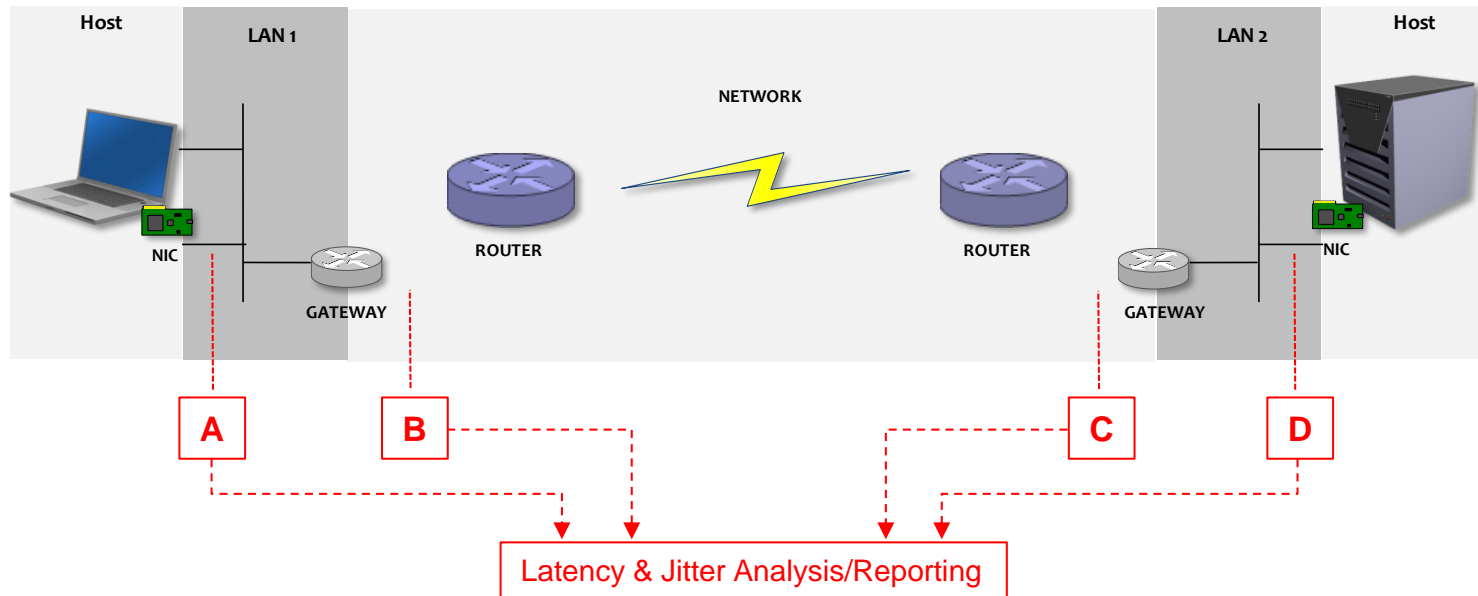
# Context & Scope of This Short Document



- Context: hardware time stamping to enable latency measurement, analysis, and reporting
- Scope: describe simple experiments that can be conducted in any customer lab to compare accuracy/precision of the time stamping feature of different solutions

# Monitor Latency/Jitter with HW Probes

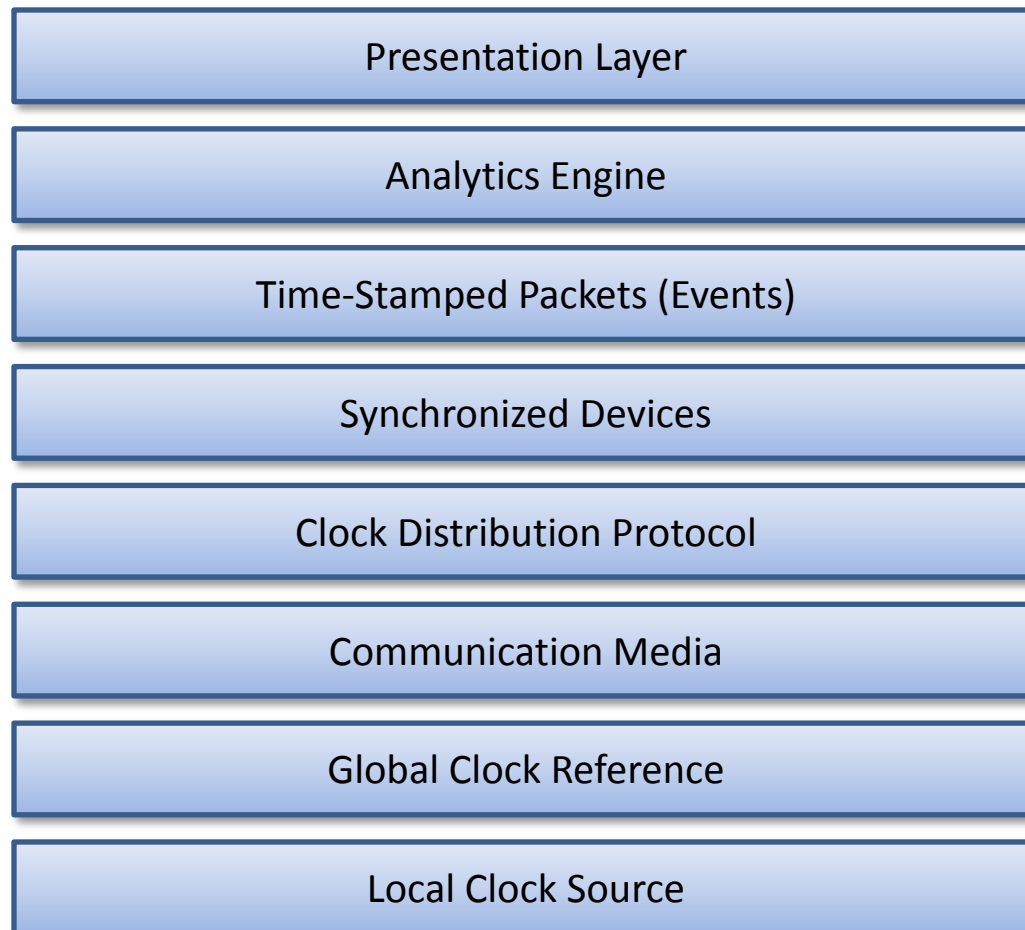
- The solution: independent HW measurement



- Eliminate stochastic variability of queues, SPAN ports, and SW

# One-Way Measurement Base Architecture

- Measurement is only as accurate as the weakest link
  - Must have clock reference, distribution, synchronization

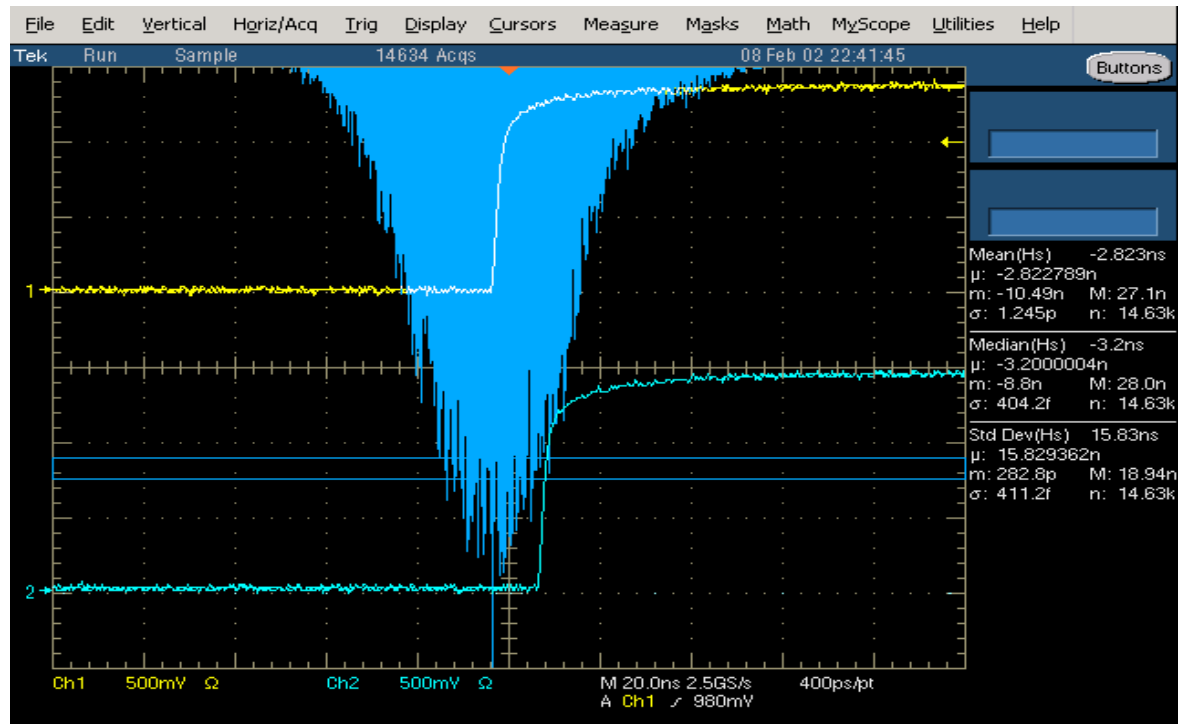


# Reference Result

- Purpose: determine a bound on the accuracy that can be achieved by using GPS (or other) master clocks
  - Note that in addition to the inherent inaccuracy of the GPS themselves, additional inaccuracy will be introduced by the clock synchronization media and clock distribution protocols
- Setup: two independent GPS receivers at the same physical location with PPS (Pulse Per Second) output
- Methodology: compare the variability between the PPS outputs of both GPS devices by using an oscilloscope

# Commercial GPS Clocks are not Perfect

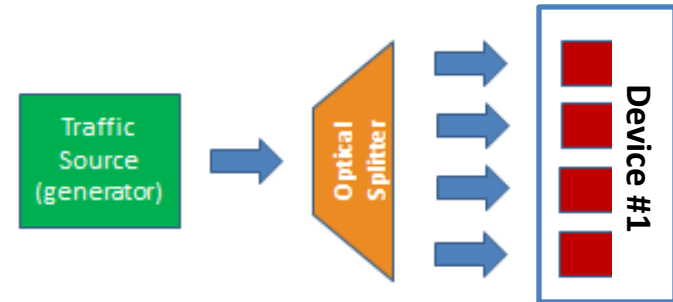
Oscilloscope Screen Capture



- Histogram of PPS discrepancy between two specific devices under test:  
Avg = -2.8 ns, Median = -3.2 ns, **Std = 15.83 ns**
- Implies that the variability at the 99 percentile (+/- 3 x Std) cause about 100 nanoseconds of uncertainty

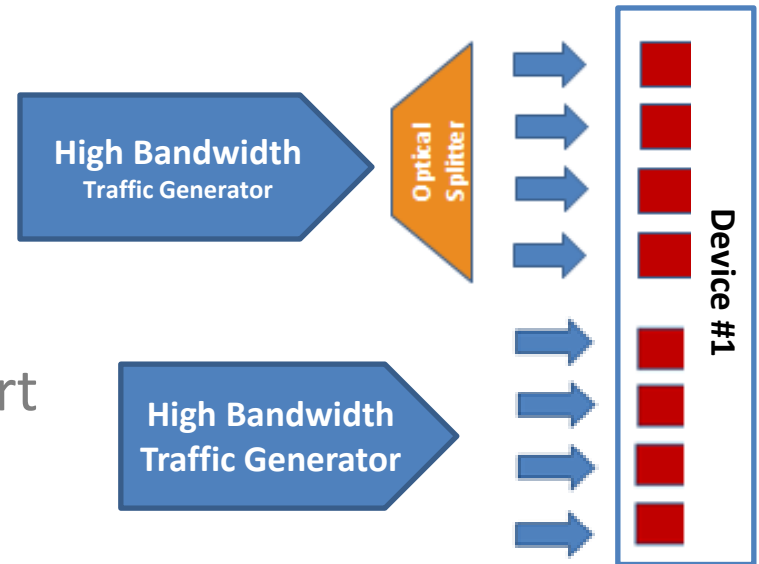
# Validation of Consistency Between Time Stamps of the Same Event at Different Ports of Same Device

- Use any traffic source (e.g. laptop, or server or tester) to generate traffic
- Use a passive optical splitter to create multiple copies (e.g. two or four) of the same packet
  - Since the optical splitter is passive, it introduces minimal variability and the packets should arrive at the time stamping ports at ~about the same time
- Create separate time stamped pcap files for each receiving port (the example above shows 4 time stamping ports)
- Compare the hardware time stamp that is attached to each duplicate of each test packet
- Expected result: variations between the time stamp of the multiple instances should be smaller than the stated accuracy of the device under test



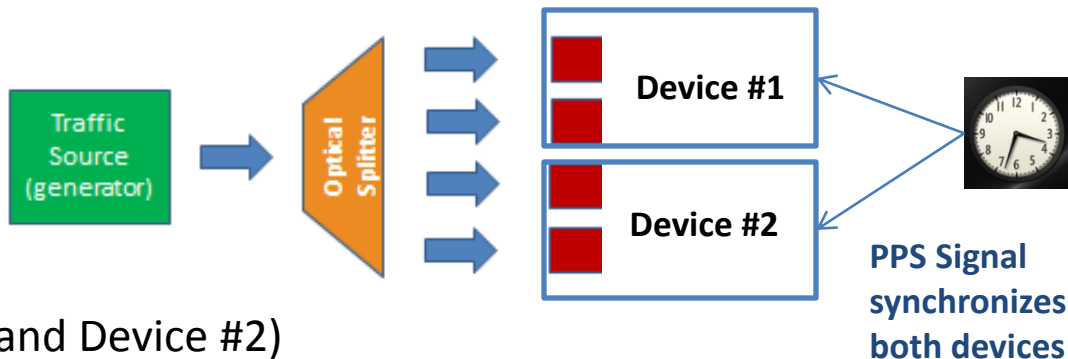
# Validation of Accuracy/Precision for Substantial Traffic Load on the Ports of the Device Under Test

- Purpose is to confirm that the traffic load on the device does not impact time stamping accuracy
- Load the device under test with additional high bandwidth traffic (min size packets, IMIX, etc.)
- Create separate time stamped pcap files for each time stamping port (the example shows 4)
- Compare the hardware time stamp that is attached to each duplicate of each test packet
- Expected result: variations between the time stamp of the multiple instances should remain consistent with previous test; the amount, speed, and type of traffic should not impact the time stamping accuracy or precision



# Validation of Consistency Between Time Stamps of Same Event at Separate Devices and Synchronization Quality

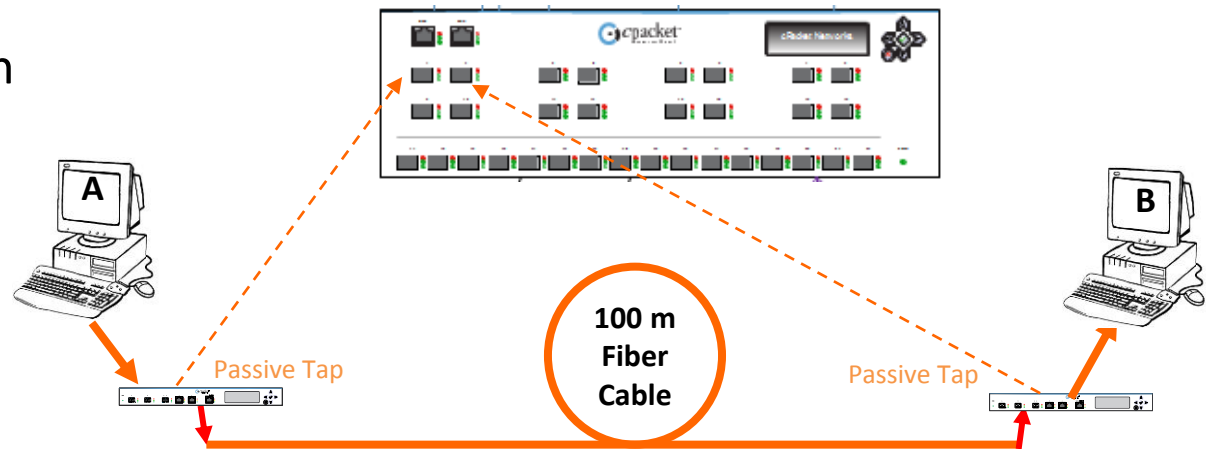
- Repeat the previous test, but use ports on two or more separate devices



- Both devices (Device #1 and Device #2) should be synchronized over PPS to the same reference (e.g. GPS)
- Create separate time stamped pcap files for each receiving port (the example above shows 4 time stamping ports)
- Compare the hardware time stamp that is attached to each duplicate of each test packet
- Expected result: variations between the time stamp of the multiple instances should be smaller than the stated accuracy of the clock synchronization to external reference

# Validation Against a Known Latency Reference for Separate Time-stamping Ports on One Device

- Connect computers A and B with fiber cable (which allows to ping from A to B)
- Tap the link on both sides of the connection with passive optical taps and use a known cable length (e.g. 100m) between the passive taps

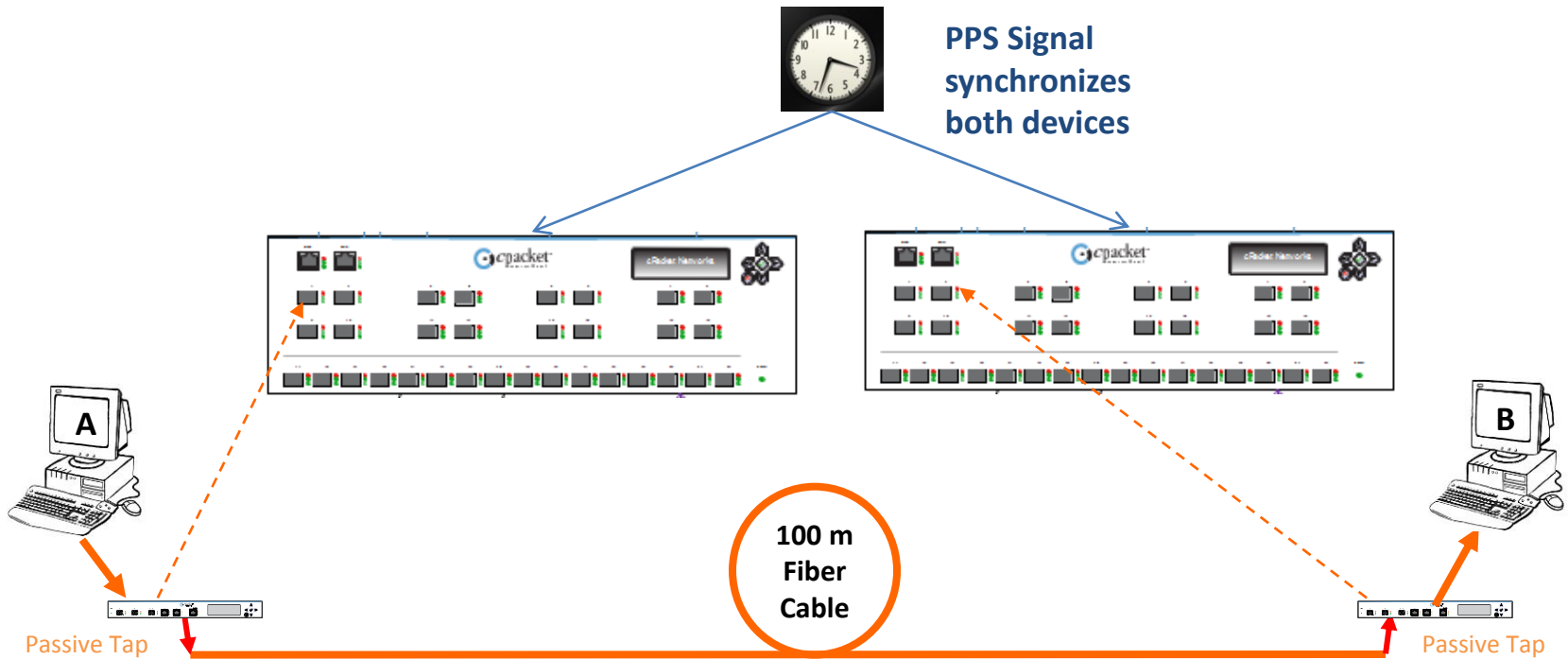


$$100 \text{ meters} \times 5 \text{ nanoseconds} = \sim 500 \text{ nanoseconds (+/-?)}$$

- Connect the tap feeds to the time stamping ports of the Device Under Test
- Create separate time stamped pcap files for each receiving port (the example above shows 4 time stamping ports)
- Expected result: subtract the time stamp on both time stamping ports and verify that it is within the target accuracy bound

# Validation Against a Known Latency Reference for Two Clock-Synchronized Devices

- Extend the setup of the previous test to two devices as described in the following diagram



$$100 \text{ meters} \times 5 \text{ nanoseconds} = \sim 500 \text{ nanoseconds (+/-?)}$$

# **Additional Notes**

# Note: cVu320G-PT provides Accuracy Reporting On-the-Fly in Real Time

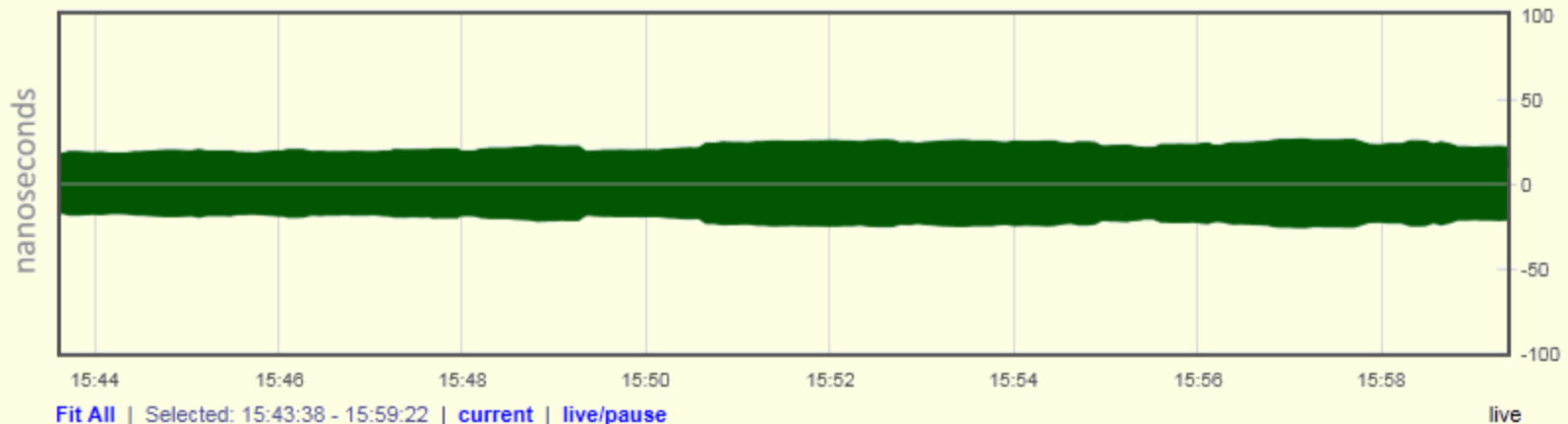
PPS Signal Detected: **YES**

Time Aligned: **YES**

Time Mode: **ABSOLUTE**

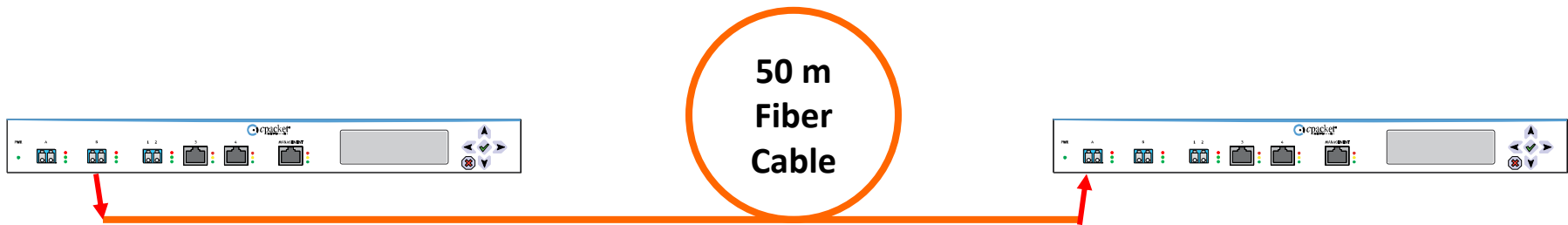
Cable Delay Compensation: 0 ns

Timestamp Accuracy: 05 Dec 2010 15:43:38 - 15:59:22



# Validation Against a Known Reference

- Validate the time stamping coherency by measure the one-way latency through a known reference (benchmark)
- Propagation delay in fiber cable is about 5 nanoseconds per meter (at ~70% of the speed of light)
- Therefore the expected result is known a-priori



$$50 \text{ meters} \times 5 \text{ nanoseconds} = \sim 250 \text{ nanoseconds}$$